











HAUS DER BARMHERZIGKEIT

HOBBIT -Towards a Robot for Aging Well

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Demographic Challenge

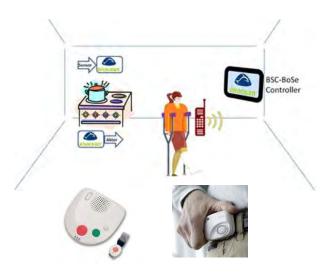
- Strong growth of population of old people
- Wish to be independent
- Fall is main reason for moving to a care facility
- At least one fall per year (in Austria, 8M people)
 - Senior citizens > 65 years 30% (N=440.000)
 - Senior citizens > 80 Jahre 50% (N=207.000)
- Direct consequences of a fall
 - Citizens > 65 years: > 50% of hospital visits due to falls
 - 14.000 fractures of thigh bones per year
 - 3 hours limit: otherwise more severe complications

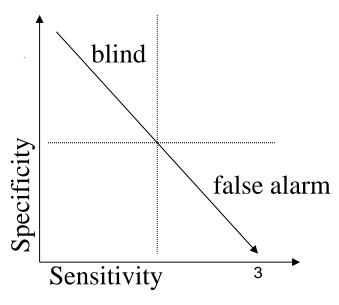


Automatic Fall Detection

- Different sensors
 - Installation in home.... high installation costs
 - On the person.... limited acceptance
- Conflict of goals
 - Sensitivity (no false alarms FA; = TP / (TP+FA)
 - Specificity(no false positivies FP; = TA / (TA+FP)







HOBBIT – A Pragmatic Approach

- HOBBIT puts user in centre of all design issues
- Approach: Mutual Care
 - User needs help from robot
 - Robot imperfect: user helps
 - E.g., learn favourite objects of user
 - E.g., open doors for robot
- And develops the needed technology





Robot: closing the gap but no replacement of personal care

HOBBIT: User-driven Approach

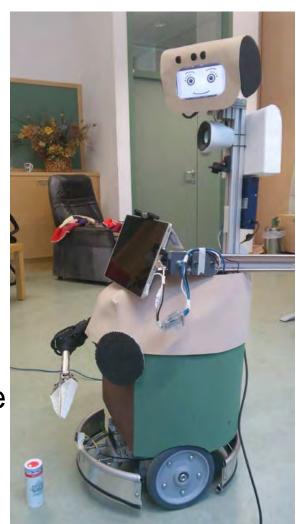
- User workshops
 - A, S, Gr
- Emphasis on Mutual Care paradigm
 - User helps robot
 - Robot helps user

COMMANDS & SERVICES	PRIORITISATION of the users (D1.2)	PRIORITISATION Considering Mutual Care implementation	PRIORITISATION
Call friend	1	-	1-
Surprise me	1	+	1+
Play Games	1	+	1+
Go recharging	2	+	2
Follow Me	2	+	2
Bring Object	1	+	1+
Pick up Object	1	+	1+
Learn Object	1	+	1+
Call robot	1	+	1+
Initialization Dialogue	1	+	1+
Reminder	1	-	1-
Emergency Detection and Handling	1	•	1
Energy Management	*	-	2
AAL alarms	2	-	2
Incoming Call	1	-	1-

Fall Prevention and Acceptance

- User-centred MMUI
 - Reachable screen
 - Touch, voice, gestures
- Pick-up, learn, bring object
 - Turntable
 - Tray to store objects
- Emergency detection
 - MMUI: Touch, button, voice, posture
- Integration on small platform





HOBBIT Summary

- Introduce robot to user by trusted person
- Mutual Care: robot and user help each other
 - Attachment theory (pets, tamagochi)
- Learn object
 - Engage user & make her feel self-confident
- Pick-up object more important than bring object
 - Emotions to express needs: asking for reward
- Detect emergency situation
 - Hand shake before alarm, Calming dialogue