



Haus der Barmherzigkeit Akademie für Altersforschung

HOBBIT – The Mutual Care Robot

FP7-ICT-2011-7

# SEVENTH FRAMEWORK PROGRAMME

# **ICT - Information and Communication Technologies**



# HOBBIT The Mutual Care Robot

Collaborative project

# D9.1 Project Web-Page

Organisation name of lead partner: Technische Universität Wien

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Abstract	Homepage for presenting the project, to stimulate discussion and to report about findings.

HOBBIT is an initiative of Technische Universitaet Wien, Austria (co-ordinator); Otto Bock Mobility Solutions GMBH, Germany (OBMS); Hella Automation GMBH, Austria (HELLA); Foundation for Research and Technology Hellas, Greece (FORTH); Lunds Universitet, Sweden (ULUND); Akademie fur Altersforschung am Haus der Barmherzigkeit, Austria (AAF).

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# HOBBIT project website

# 1 Introduction

The aim of this deliverable is to have a general HOBBIT project website, to stimulate discussion and to report about findings. The site informs about the project, about project progress, and results.

The HOBBIT website will be advertised to and linked with other information sites such as consortium partners' websites and related multipliers. TUW will continually monitor access to the site and all partners will be involved to suggest improvements to increase the site's accessibility and usage.

The Public HOBBIT website is work in progress. This means that more content will be added as the project matures. Also, additional functionality will be added as necessary in the future. This report focuses on the status of the site after the last biannual Project Meeting (September 2012).

# 2 Overview

The following tree shows the publicly accessible pages of the HOBBIT website.

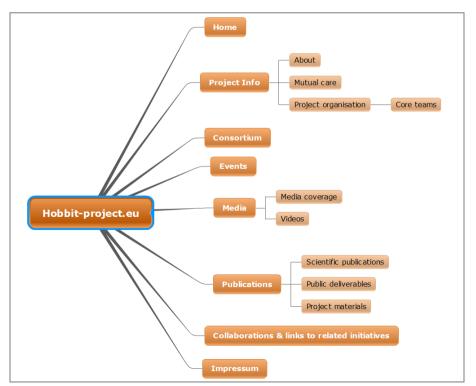


Figure 1: HOBBIT website menu structure



# 2.1 Web layout

The HOBBIT project website has a very simple but effective layout:

- The design follows the corporate identity of the project: orange from the HOBBIT logo with white and light grey background (like in internal documents of the project).
- All the pages have the same display of items. As marked (in red) in Figure 2, the main items are:
  - $_{\odot}$  The HOBBIT logo heading the page with TUW and EC logos at each side
  - The website menu (on the left side)
  - A news section (on the left side below the menu): will show latest news of the project
  - The content in the middle
  - HOBBIT FP7 project acknowledgement and disclaimer text with the FP7 logo.

	N Hobbit	0
Home	(title)	
Project Info Participate Consortium Events Media Publications Collaborations & Inska to related initiatives Instructives I	(content)	
	The research realing to these results has received funding from the European Union Seventh Pramework Programme (PP100010013) under gath agreement of 202148. Disclamme: The Versa europeased in this document are solely those of the authors. The Union is not liable for any use that may be made of the informat compared them.	

Figure 2: HOBBIT website display of items



# 3 Pages

### 3.1 Home

The content of the *Home* page consists of a short introduction to the FP7 project: its new approach and a picture introducing the "mutual care" concept.

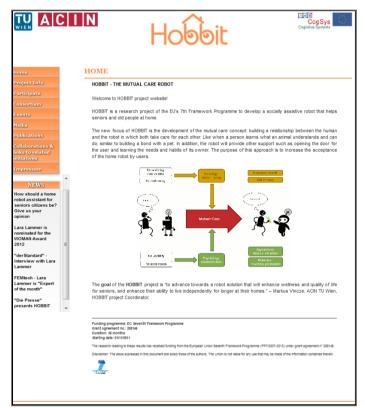


Figure 3: HOBBIT "Home" website page

# 3.2 Project Info

The *Project Info* section presents information on the project itself and is divided into three sections: "About", "Mutual care" and "Project organisation".

#### 3.2.1 About

In this sub-page, we introduce to the reader the challenge that HOBBIT will respond to, the current state-of-the-art in social assistive robotics and explain what the new approach of the HOBBIT project is.

At the end of the page, some general projects facts are displayed.

#### "Project Web-Page"



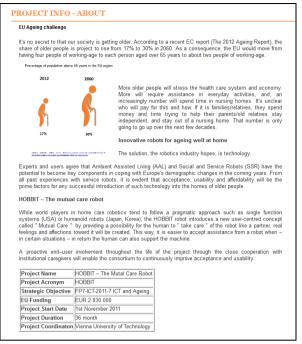


Figure 4: HOBBIT "About" website page

#### 3.2.2 Mutual care

Here the mutual care concept, its implications and the interpretation of it in HOBBIT will be explained and revised as the project advances.

Currently a general framework of "mutual care" is displayed to give the reader or web user an idea of this concept.

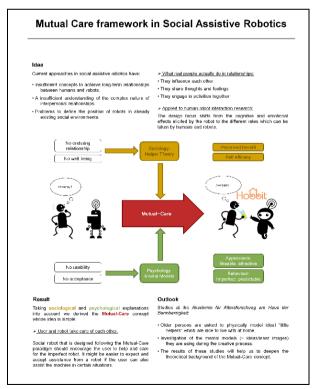


Figure 5: HOBBIT "Mutual care" website page



#### 3.2.3 Project organisation

In this sub-page, the matrix organisation structure of the project is presented, where there is a cross-cutting of knowledge and information between work packages and the design & developments core teams.

Core	Coor	rdinato		
			_	
team Use		WP5 (	WP6 WP7 WF	P8 WP9 WP10
Desig Imple	em	Ŀ		
The wor	rk packages and their partner leaders are the			
he wor	WP NAME	LEAD		
he wor	WP NAME User Involvement and Specifications	LEAD AAF		
he wor WP WP1 WP2	WP NAME User Involvement and Specifications User-Interface and Acceptance Design	LEAD AAF ULUND		
he wor WP WP1 WP2 WP3	WP NAME User Involvement and Specifications User-Interface and Acceptance Design Robot-User Interaction and Behaviour Model	LEAD AAF ULUND		
The wor WP WP1 WP2 WP3 WP4	WP NAME User Involvement and Specifications User-Interface and Acceptance Design Robot-User Interaction and Behaviour Model Robot-Enviroment (AAL) Interaction	LEAD AAF ULUND TUW HEL		
he wor WP WP1 WP2 WP3 WP4 WP5	WP NAME User Involvement and Specifications User-Interface and Acceptance Design Robe-User Interaction and Behaviour Model Robet-Environment (AAL) Interaction Localisation, Tracking and Gesture Interface	LEAD AAF ULUND TUW HEL		
he wor WP WP1 WP2 WP3 WP4 WP5 WP6	WP NAME User Involvement and Specifications User-Interface and Acceptance Design Robet-User Interaction and Behaviour Model Robot-Environment (AAL) Interaction Localisation, Tracking and Gesture Interface Robot Navigation and Manipulation	LEAD AAF ULUND TUW HEL FORTH		
he wor WP1 WP2 WP3 WP4 WP5 WP6 WP7	WP NAME User Involvement and Specifications User Interface and Acceptance Design Robot-User Interaction and Behasiour Model Robot-Environment (AAL) Interaction Localisation, Tracking and Gesture Interface Robot Navigation and Manipulation Platform Design and Development	LEAD AAF ULUND TUW HEL FORTH TUW	i—i—i	
he wor WP1 WP2 WP3 WP4 WP5 WP6 WP7 WP8	WP NAME User Involvement and Specifications User-Interface and Acceptance Design Robot-User Interaction and Behaviour Model Robot-Environmeri (AAL) Interaction Localisation, Tracking and Gesture Interface Robot Navigation and Manipulation Platform Design and Development System Integration and Assembly	LEAD AAF ULUND TUW HEL FORTH TUW OB	1-1-1	

Figure 6: HOBBIT "Project organisation" website page

#### 3.2.3.1 Core teams

In this sub-page, the role of the three core teams is introduced. An impression of how the project team will work and how the design of the robot system will be developed is given.



Figure 7: HOBBIT "Core teams" website page



# 3.3 Participate

The *Participate* page has the purpose of engaging the website users in activities and tasks from the project, making it more attractive to key stakeholders such as primary and secondary users of social robotics or the related scientific community.

Dea	r participant,
wor son	i your answers, as potential user, you provide an essential input to the question of how a robotic assistant cou in a home. Please imagine you have a robotic assistant in your home. We are very happy if you could spen terms answering the following questions. Please choose one answer that in your opinon is most sulable for question. There are no wrong answers. What counts is your personal opinion. Your data will be coded an yoed in anonymous form. Results will be published on the project home page. www.hobbit.project.et u
	questionnaire comprises 4 different web links with short questions. Please answer to the questions in all page links. Thank you for your contribution!
	HOBBIT Questionnaire for Primary User Assessment - part 1/4
	User general information
	* 1. In what year were you born? (enter 4-digit birth year; for example, 1976)
	#2. What is your gender?
	fonds     fonds
	*3. Kumber of persons in the household
	07
	C new
	Contrag
	3BIT Questionnaire for Primary User Assessment – part 1/4:
http	//www.surveymonkey.com/s/2FKKR62"
	3BIT Questionnaire for Primary User Assessment – part 2/4:
	//www.surveymonkey.com/s/JXXMXYN
map	//www.survey.com/s/3XAWX11
HO	3BIT Questionnaire for Primary User Assessment – part 3/4:
	//www.surveymonkey.com/s/JXBTYCH

Figure 8: HOBBIT "Participate" website page

## 3.4 Consortium

The *Consortium* page lists all project partners including logos with the link to their website, the key people involved and their contact emails or their profile web page from their organisation if available.



Figure 9: HOBBIT "Consortium" website page



# 3.5 Events

The Events page lists upcoming and past events relevant to the project.

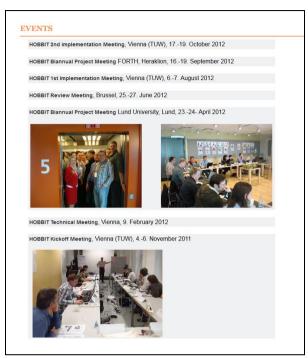


Figure 10: HOBBIT "Events" website page

## 3.6 Media

The Media page shows news relevant to the project.

#### 3.6.1 Media coverage

In this sub-page, all news (written or visual) reporting on the HOBBIT project and its members will be listed providing a URL to the news.

Press	
Lara Lammar is nominated for the WOMAN-Award 2012	
For more infos about the WOMAN-Award see here (in german);	
"Psychologie in Österreich - HOBBIT the Mutual Care Robot"	
Psychologie in Österreich reports about HOBBIT	
Read the article here (in german);	
"Kronen Zeitung - "Ein R2-D2 zum Putzen"	
Kronen Zeitung reports about KOROS	
Read the article here (in german):	
"derStandard - Der Traum vom Roboter für alles" – 12. June 2012	
Interview with Lara Lammer about HOBBIT	
Read the interview here (in german):	
derStandard Interview Lara Lammer	
"FEMtech - Expert of the month June 2012" - June 2012	
Lara Lammer is "Expert of the month" Read the article here (in german):	
FEMtech	
Read the interview here (in german):	
Interview Lara Lammer - FEMtech	
"Auf den Hund gekommen - Wiener Forscher entwickeln einen leistbaren Haushaltsrobot	ler"
"Die Presse" presents HOBBIT	
download article (in German)	

Figure 11: HOBBIT "Media coverage" website page



#### 3.6.2 Videos

In this section, future videos from the project will be displayed.

#### 3.7 Publications

The Publications page shows public written or visual material resulting from Hobbit project.

#### 3.7.1 Scientific publications



Figure 12: HOBBIT "Scientific publications" website page

#### 3.7.2 Public deliverables

In this section abstracts from public deliverables resulting from the project will be displayed.

#### 3.7.3 Project materials

Project materials will contain general dissemination materials on HOBBIT.



# 3.8 Collaborations and links to related initiatives

In this page, we show with which projects or initiatives on social assistive robotics HOBBIT either, actively collaborates or follows closely, to build on.

Netv	rorks
	The <u>Ambient Assisted Living Joint Programme (AAL JP)</u> is a funding activity running from 2008 to 2013, with the aim of enhancing the quality of life of older people and strengthening the industrial base in Europy through the use of information and Communication Technologies (ICT). Therefore, the AAL JP is an activit that operates in the field of services and actions to enable the active ageing among the population.
Proje	cts
	Integrated cognitive assistive and domotic companion robotic systems for ability and securit (COMPANIONABLE) Multi-Purpose Mobile Robot for Ambient Assisted Living (FLORENCE). The Florence project with it multipupurpose mobile robot platform will pioneer the use of robots in delivering new kinds of AAL service to elderly persons and their caretakers. The main objective of Florence is to make this concept acceptable for the users and cost effective for the society and care givers. HERMES - Cognitive care and guidance for active aging (HERMES) Knowledgable SErvice Robots for Aging (KSERA). UNIVERsal open platform and reference Specification for Ambient Assisted Living (UNIVERSAAL) The Austrian project <u>#HOME</u> will develop an assistive home environment for elderly persons, covering far recognition and prevention, activity monitoring and social integration of elderly persons and their carers. The EU funded FP7 project <u>Robots and</u> . The robots use the World Wide Web for robots including nurse-bots an socially assistive robots (SAR). The robots use the World Wide Web to store and retrieve learned tasks and actions. This enables robots to learn from ach other and apply in their own setting. In the INTERREG-IVC project <u>Robots MD</u> , develop a home care robot which monitors and detects critica stuators which need promit indical attention for older persons or people with activacusual diseases. DOMEQ, an AAL Project, focuses on the development of an open robotic platform for the integration and adaptation of personalized hownecare services, as well as cognitive and physical assistance.

Figure 13: HOBBIT consortium website page

## 3.9 Impressum

The *Impressum page* discloses information about the publisher (TUW), including their contact details such as name and address.



Figure 14: HOBBIT "Impressum" website page